

PROGRAM TEMPLATE – SINGLE TRACK CONFERENCE (08 December 2022)

Join Zoom Meeting

<https://polimi-it.zoom.us/j/97457801667>

Meeting ID: 974 5780 1667

DAY 1 – 2022 Edition	
Time Zone GMT +8	
09:00-09:15	Opening Session / Welcome Session
09:15	Keynote 1 Professor Xinping Yan Title: Developments and Applications of Intelligent Control Technology for Inland Waterborne Transportation in China
10:15 – 10:25	Break
10:25	Paper 1 Fixed-Time Disturbance Observer-Based Power Control of Wave Power Generation System
10:45	Paper 2 Disturbance observer-based fast fixed-time nonsingular terminal sliding-mode formation control for autonomous underwater vehicles
11:05	Paper 3 Sailboat Path Following Control Based on LOS with Sideslip Angle Observation and Finite-Time Backstepping
11:25	Paper 4 A Deep Learning-Based Method for Drivers' Shoe-Wearing Recognition
11:45	Paper 5 Coordinate Attention and Transformer neck-based Marine Organism Detection
12:05	Paper 6 An Improved Regression Partial Least Squares Method for Quality-Related Process Monitoring of Industrial Control Systems
12:25 – 14:00	Lunch
14:00	Paper 7 A Novel Stochastic Event-Based Feedback Watermark for Replay Attack Detection
14:20	Paper 8 A Cascade Finite-Time Nonlinear Extended State Observer for Active Disturbance Rejection Control
14:40	Paper 9 A Learning-based driving style classification for intelligent vehicles
15:00	Paper 10 CADM: Confusion Model-based Detection Method for Real-drift in Chunk Data Stream
15:20 – 15:30	Break
15:30	Keynote 2 Prof. Md Atiqur Rahman Ahad Title: Sensors & Skeleton for Healthcare: Some Examples
16:30	Keynote 3 Professor Kai Cheng Title: Ultraprecision design and manufacturing of freeform surfaced 'sensor' devices and components: fundamentals, applied research, and industrial applications
17:30	Closing the conference.